

# Formalizing Projective Geometry in Coq

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# Outline

- 1 Related Work - Motivations
- 2 Plane Projective Geometry
- 3 Space Projective Geometry
- 4 Results and Next Moves

## Related Work

- Gilles Kahn [Kah95]
- Christophe Dehlinger, Jean-François Dufourd and Pascal Schreck [DDS00]
- Laura Meikle and Jacques Fleuriot [MF03]
- Frédérique Guilhot [Gui05]
- Julien Narboux [Nar04, Nar07]
- Jean Duprat [Dup02]
- Bezem and Hendriks [BH08]

# Motivations

## Projective Geometry ?

- Only considers incidence properties.
- In 2D, two lines always intersect.
- A simple but powerful framework
- Flats, ranks and a proof of Desargues theorem
- Further work: a certified prover for collinearity/planarity properties (à la Schreck) and a certified formal solver

# Plane Projective Geometry

- Objects: Points, Lines
- An Incidence relation between Points and Lines
- We assume decidability of Incidence

$$\forall P : \textit{Point}, \forall l : \textit{Line}, \{\textit{Incid } P \ l\} \{\neg \textit{Incid } P \ l\}$$

- Decidability for Point (resp. Line) equality is proved !

# Axioms for Projective Plane Geometry

- Axiom Line Existence

$$\forall A B : Point, (\exists l : Line, A \in l \wedge B \in l)$$

- Axiom Point Existence

$$\forall l m : Line, (\exists A : Point, A \in l \wedge A \in m)$$

- Axiom Line Unicity

$$\begin{aligned} &\forall A B : Point, A \neq B \Rightarrow \\ &\forall l m : Line, A \in l \wedge B \in l \wedge A \in m \wedge B \in m \Rightarrow l = m \end{aligned}$$

- Axiom Point Unicity

$$\begin{aligned} &\forall l m : Line, l \neq m \Rightarrow \\ &\forall A B : Point, A \in l \wedge A \in m \wedge B \in l \wedge B \in m \Rightarrow A = B \end{aligned}$$

## More Axioms

**Axiom Uniqueness** (subsumes both unicity axioms)

$$\forall A B : \textit{Point}, \forall l m : \textit{Line}, \\ A \in l \Rightarrow B \in l \Rightarrow A \in m \Rightarrow B \in m \Rightarrow A = B \vee l = m$$

**Axiom Four Points**

$$\exists A : \textit{Point}, \exists B : \textit{Point}, \exists C : \textit{Point}, \exists D : \textit{Point}, \\ \textit{distinct} A B C D \wedge \\ (\forall l : \textit{Line}, (A \in l \wedge B \in l \Rightarrow C \notin l \wedge D \notin l) \wedge \\ (A \in l \wedge C \in l \Rightarrow B \notin l \wedge D \notin l) \wedge \\ (A \in l \wedge D \in l \Rightarrow B \notin l \wedge C \notin l) \wedge \\ (B \in l \wedge C \in l \Rightarrow A \notin l \wedge D \notin l) \wedge \\ (B \in l \wedge D \in l \Rightarrow A \notin l \wedge C \notin l) \wedge \\ (C \in l \wedge D \in l \Rightarrow A \in l \wedge B \in l))$$

## Another system

### Alternative Axioms (replacing Axiom Four Points)

- Axiom Three Points

$\forall l : \text{Line},$

$\exists ABC : \text{Point}, (A \neq B \wedge B \neq C \wedge A \neq C) \wedge A \in l \wedge B \in l \wedge C \in l$

- Axiom Lower Dimension

$\exists l_1 : \text{Line}, \exists l_2 : \text{Line}, l_1 \neq l_2$

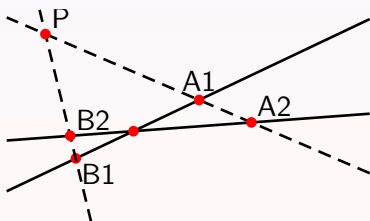


## Properties

- Equivalence of the two axiom systems
- Decidability of point (resp. line) equality derived from decidability of incidence :

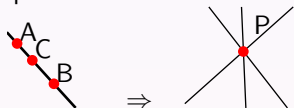
$$\forall A : \text{Point}, \forall l : \text{Line}, \{ \text{Incid } A \ l \} + \{ \neg \text{Incid } A \ l \}$$

- Flats and their characterization (in a couple of minutes...)
- Lines as sets of points and bijections

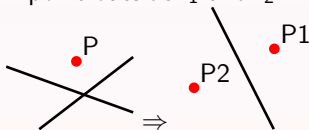


# Duality

- A functor from Projective Plane Geometry to itself
- Application: proving some theorem automatically
  - 3 points on a line  $\rightarrow$  3 lines through a point

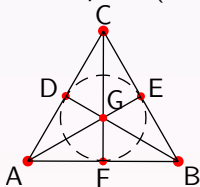


- 1 point outside  $l_1$  and  $l_2 \rightarrow$  1 line not through  $P_1$  and  $P_2$



# Models

- Finite Models  
 $PG(dim, b)$  where given a point on a line,  $b$  is the number of other lines through the point.
  - Fano's plane ( =  $PG(2, 2)$  the smallest projective plane)



- $PG(2,5)$  (31 points and as many lines, thus 923 521 cases)
- Infinite Model: Homogeneous Coordinates
- Remark : this raises scalability issues in 3D

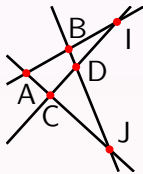
# Axioms for Space Projective Geometry (I)

## Axiom Line Existence

$$\forall A B : \text{Point}, \exists I : \text{Line}, A \in I \wedge B \in I$$

## Axiom Pasch (replaces Axiom Point Existence)

$$\forall ABCD : \text{Point}, \forall I_{AB} I_{CD} I_{AC} I_{BD} : \text{Line}, \text{dist4 } ABCD \wedge \\ A \in I_{AB} \wedge B \in I_{AB} \wedge C \in I_{CD} \wedge D \in I_{CD} \wedge \\ A \in I_{AC} \wedge C \in I_{AC} \wedge B \in I_{BD} \wedge D \in I_{BD} \wedge \\ (\exists I : \text{Point}, I \in I_{AB} \wedge I \in I_{CD}) \Rightarrow$$



$$\exists J : \text{Point}, (J \in I_{AC} \wedge J \in I_{BD})$$

## Axiom Uniqueness

$$\forall A B : \text{Point}, \forall I m : \text{Line}, \\ A \in I \Rightarrow B \in I \Rightarrow A \in m \Rightarrow B \in m \Rightarrow \\ A = B \vee I = m$$

## Axioms for Space Projective Geometry (II)

### Axiom Three Points

$$\forall l : \text{Line}, \exists ABC : \text{Point}, (A \neq B \wedge B \neq C \wedge A \neq C) \wedge \\ A \in l \wedge B \in l \wedge C \in l$$

### Axiom Lower Dimension

$$\exists l_1 l_2 : \text{Line}, \neg \exists p : \text{Point}, p \in l_1 \wedge p \in l_2$$

### Axiom Upper Dimension

$$\forall l_1 l_2 l_3 : \text{Line}, \text{dist3 } l_1 l_2 l_3 \rightarrow \\ \exists l_4 : \text{Line}, \exists J_1 : \text{Point}, \exists J_2 : \text{Point}, \exists J_3 : \\ \text{Point}, (\text{dist3 } J_1 J_2 J_3) \wedge \\ (\text{Intersect\_In } l_1 l_4 J_1) \wedge (\text{Intersect\_In } l_2 l_4 J_2) \wedge \\ (\text{Intersect\_In } l_3 l_4 J_3)$$

## Flats and Ranks (I)

- Sets as their characteristic function ( $Point \rightarrow Prop$ )

- Definition

A **flat** is a set of points such that the entire line defined by  $A$  and  $B$  lies in the flat whenever  $A$  and  $B$  belong to it.

$$flat(v) = \forall AB : Point, v A \rightarrow v B \rightarrow A \neq B \rightarrow$$

$$\forall I : Line, Incid A I \rightarrow Incid B I \rightarrow \forall C : Point, Incid C I \rightarrow v C$$

- The empty set  $\emptyset$ , singletons, lines, planes and the whole space are flats:
  - Empty:  $fun(p : Point) \Rightarrow False$
  - Singleton  $x$ :  $fun(p : Point) \Rightarrow p = x$
  - Line  $l$ :  $fun(p : point) \Rightarrow p \in l$
  - Plane  $l_1 l_2$   $l_1 \neq l_2$   $l_1 \cap l_2 \neq \emptyset$ :  $fun(x : Point) \Rightarrow$   
 $\exists I : Line, x \in I \wedge \exists I, \exists J, I \neq J \wedge$   
 $Intersect\_In I l_1 I \wedge Intersect\_In I l_2 J$
  - Space:  $fun(p : Point) \Rightarrow True$

## Flats and Ranks (II)

- Characterization of flats  
The only flats in dim. 3 are the empty set, singletons, lines, planes and the whole space.
- Rank of a set of points is defined by flat-closure of this set.  
This flat is either the empty set ( $\text{rk}=0$ ), or a singleton set ( $\text{rk}=1$ ), or a line ( $\text{rk}=2$ ), etc.
- Informally, rank corresponds to  $\text{dim} + 1$ . It ranges from 0 ( $\emptyset$ ) to 4 (the whole space).
- Collinearity or Planarity expressed with ranks : examples
  - $\text{rk}(A,B)=1$  means A equals B
  - $\text{rk}(A,B,C)=2$  means A, B and C are collinear with at least 2 distinct
  - $\text{rk}(A,B,C,D)=3$  means A, B, C and D are coplanar with at least 3 distinct
  - $\text{rk}(A,B,C,D)=4$  means A,B, C and D are not coplanar and all distinct

# Matroid Properties for Rank

- Rank verifies matroid properties.
- Properties

$$(1) rk(\emptyset) = 0$$

$$(2) e \subset e' \rightarrow rk(e) \leq rk(e')$$

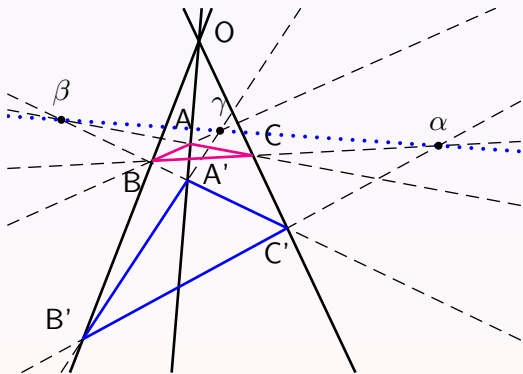
$$(3) rk(e' \cup e) + rk(e' \cap e) \leq rk(e') + rk(e)$$

- scale ? we can proceed with one singleton at a time (rather than using (3))
- What about  $rk(x) = 1$ ,  $rk(x, y) = 2$  and  $rk(x, y, z) = 3$  ?



# Proving Desargues' with ranks (I)

A 3D version of Desargues' theorem



## Proving Desargues' with ranks (II)

- Formal Statement

$rk(a, A, O) = 2, rk(b, B, O) = 2, rk(c, C, O) = 2$  (perspective)

$rk(a, b, c) = 3, rk(A, B, C) = 3$  (2 triangles)

$rk(A, B, C, a, b, c) = 4$  (not coplanar)

$rk(A, B, \gamma) = 2, rk(a, b, \gamma) = 2$  (building  $\gamma$ )

$rk(A, \beta, C) = 2, rk(a, \beta, c) = 2$  (building  $\beta$ )

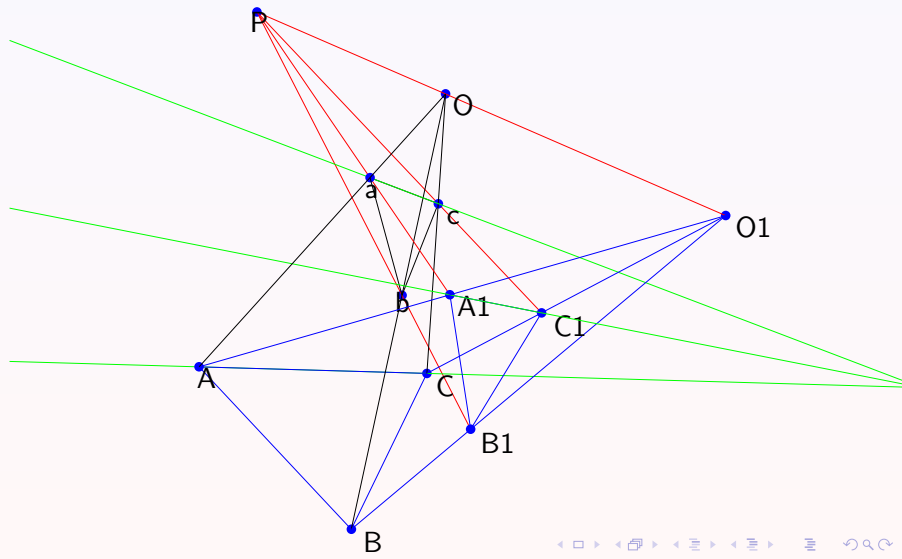
$rk(\alpha, B, C) = 2, rk(\alpha, b, c) = 2$  (building  $\alpha$ )

$rk(M, N) = 2 \forall MN \in \{a, b, c, A, B, C\}$  where  $M \neq N$

$\rightarrow rk(\alpha, \beta, \gamma) = 2$

- Lifting into 3D one of the triangles
- Projecting back is not required as  $\alpha, \beta$  and  $\gamma$  are on the 3 relevant lines.

# Desargues' theorem



## Main Results

- Equivalence of axiom systems
- Decidability of equality (both for points and lines)
- Duality
- Models in 2D (Fano,  $PG(2,5)$ )
- Flats characterization in 2D and 3D
- Matroid structure for rank
- Desargues' theorem

## Next steps

- Write more proofs (currently around 10000 lines)
- Write more tactics to solve goals automatically:  
successful experiments have been carried out and need improvement
- Complete Desargues' proof (3D lifting, particular cases)
- In Plane PG, prove Pappus implies Desargues (Hessenberg's theorem)



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